

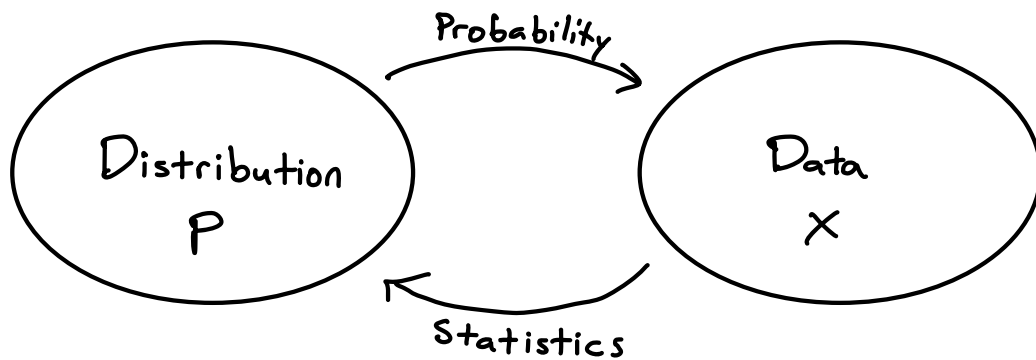
# Statistical models and decisions

## Outline

- 1) Statistical models
- 2) Estimation
- 3) Decision theory

# Statistical Models

## Probability vs statistics



Probability: Distribution  $P$  fully specified  
What can we say about  $X \sim P$ ?  
Deductive

Statistics: Observe data  $X$  from unknown dist.  $P$   
What can we conclude about  $P$ ?  
Inductive

Statistical model Family  $\mathcal{P}$  of candidate  
probability distributions for data  $X$

Assume  $X \sim P$  for some  $P \in \mathcal{P}$  (don't know which)  
 $X$  yields evidence about which  $P$  (hopefully)

# Coin flipping

Recall: 48 humans tossed coins  $n = 350,757$  total times  
 $X = 178,079$  landed same-side up.

## Model 1:

All flips independent, with same probability  $\theta \in (0,1)$

$$\Rightarrow X \sim P_{\theta} = \text{Binom}(n, \theta)$$

$\uparrow$  known $\uparrow$  unknown (varies over model)

Probability mass function  $p_{\theta}(x) = \binom{n}{x} \theta^x (1-\theta)^{n-x}$   
for  $x = 0, 1, \dots, n$

$$\mathcal{P} = \{P_{\theta} : \theta \in (0,1)\}$$

## Model 2: Flippers have different biases

$$\Rightarrow X_i \stackrel{\text{ind.}}{\sim} \text{Binom}(n_i, \theta_i) \quad i=1, \dots, 48$$

$\uparrow$  flipper is same-side flips $\uparrow$  i's total flips $\uparrow$  i's same-side prob.

Parameter vector  $(\theta_1, \dots, \theta_{48}) \in (0,1)^{48}$

## Model 3: Biases change over time, non-increasing

$$\Rightarrow X_{i,t} \stackrel{\text{ind.}}{\sim} \text{Bernoulli}(\theta_{i,t}) \quad \begin{array}{l} i=1, \dots, 48 \\ t=1, \dots, n_i \end{array}$$

$\uparrow$   
 $t^{\text{th}}$  flip by flipper  $i$

Constrain  $\theta_{i,1} \geq \theta_{i,2} \geq \dots \geq \theta_{i,n_i}$  ( $n$  parameters!)

[Question: Why does the sample space keep changing?]

# Parametric vs. Nonparametric

Parametric model dist.s indexed by parameter  $\theta \in \Theta$

$$\mathcal{P} = \{P_\theta : \theta \in \Theta\}$$

Typically  $\Theta \subseteq \mathbb{R}^d$ ,  $d$  called model dimension

Nonparametric model no natural way to index  $\mathcal{P}$

Still usually makes assumptions, e.g.

- independence
- shape constraints (e.g.  $P$  has  $\downarrow$  density on  $\mathbb{R}_+^d$ )

Example  $X_1, \dots, X_n \overset{\text{iid}}{\sim} P$   $P$  any distr. on  $\mathbb{R}$   
↖ (independent & ident. distr.)

$$\mathcal{P} = \{P^n : P \text{ is a distr. on } \mathbb{R}\} \quad (\text{for } X = (X_1, \dots, X_n))$$

Boundary between parametric & non-parametric models is somewhat shaggy.

We can use "parametric notation"  $\mathcal{P} = \{P_\theta : \theta \in \Theta\}$  wlog  
(could take  $\Theta = \mathcal{P}$ ,  $\Theta = \mathcal{P}$ )

## Estimation

Observe  $X \sim \text{Binom}(n, \theta)$   $\theta \in (0, 1)$  unknown

Ask: What is  $\theta$ ?

Skeptic's answer: Could be anything

Any  $X \in \{0, \dots, n\}$  is possible under any  $\theta$

Bayesian answer: Assume  $\theta$  random with known prior

$\Rightarrow$  Conditional (posterior) distribution for  $\theta$  given  $X$

Frequentist answer: Inductive behavior

Find a method for using  $X$  to estimate  $\theta$ , e.g.  $\delta_\theta(X) = \bar{X}/n$

Show it generally works well for any  $\theta$

Doesn't really answer question about this  $\theta$  and this  $\delta(X)$

General setup Model  $\mathcal{P} = \{P_\theta : \theta \in \Theta\}$  (or non-par.  $\mathcal{P}$ )

Estimand  $g(\theta)$  (or  $g(P)$ )

Observe  $X$ , calculate estimate  $\delta(X)$

$\delta(\cdot)$  called estimator.

We want to evaluate & compare estimators

# Loss and Risk

Loss function  $L(\theta, d)$

Disutility of guessing  $g(\theta) = d$

Typically non-negative, with  $L(\theta, d) = 0$  iff  $d = g(\theta)$

[Different for every realization]

Squared error loss:  $L(\theta, d) = (d - g(\theta))^2$

Risk function: expected loss of an estimator

$$R(\theta; \delta(\cdot)) = \mathbb{E}_{\theta} [L(\theta, \delta(x))]$$

↑ tells us which parameter value is in effect, NOT "what randomness to integrate over"

Risk for sq. error loss is mean squared error (MSE)

$$MSE(\theta; \delta(\cdot)) = \mathbb{E}_{\theta} [( \delta(x) - g(\theta) )^2]$$

## Binomial example

What is  $MSE(\theta; \delta_0)$ ? ( $\delta_0(x) = \frac{x}{n}$ )

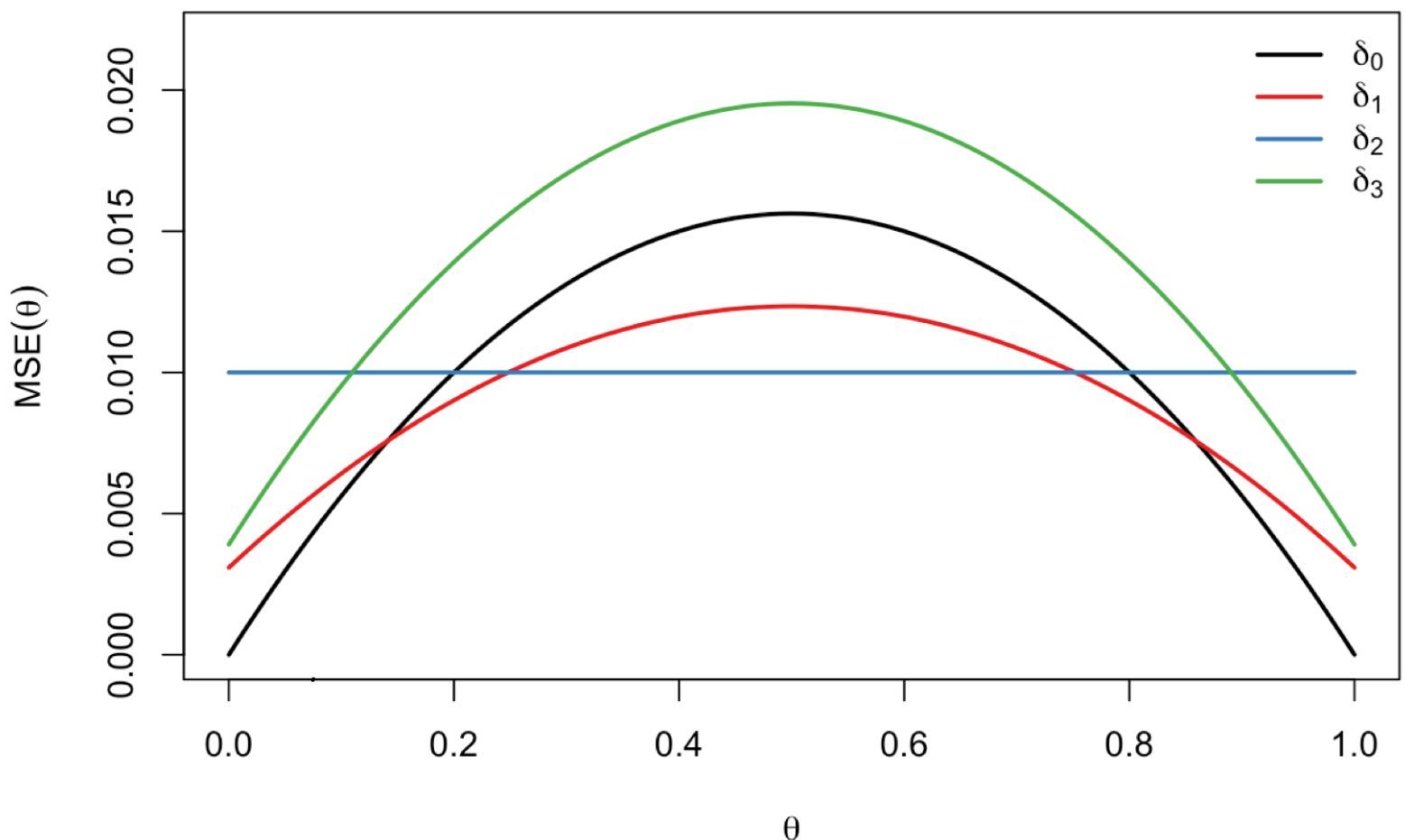
$$E_{\theta} \left[ \frac{x}{n} \right] = \theta \quad (\text{unbiased})$$

$$\begin{aligned} \Rightarrow MSE(\theta; \delta_0) &= E_{\theta} \left[ \left( \frac{x}{n} - \theta \right)^2 \right] \\ &= \text{Var}_{\theta} \left( \frac{x}{n} \right) \\ &= \frac{1}{n} \theta(1-\theta) \end{aligned}$$

Other possibilities (based on adding "pseudo-flips")

$$\delta_1(x) = \frac{x+1}{n+2} \quad \delta_2(x) = \frac{x+2}{n+4} \quad \delta_3(x) = \frac{x+1}{n}$$

Mean squared error for binomial estimators (n=16)



## Comparing estimators

We want to choose  $\delta$  to minimize  $R$   
... but this is generally not possible

An estimator  $\delta$  is inadmissible if  $\exists \delta^*$  with

$$a) R(\theta; \delta^*) \leq R(\theta, \delta) \quad \text{for all } \theta$$

$$b) R(\theta, \delta^*) < R(\theta, \delta) \quad \text{for some } \theta$$

We say  $\delta^*$  strictly dominates  $\delta$

$\delta_1$  is inadmissible because  $\delta_0$  dominates it

Is there any uniformly best estimator  
for the binomial example?  
(all  $\theta$ )



# Resolving ambiguity

Main strategies to resolve ambiguity:

1) Summarize risk function by a scalar:

a) Average-case risk

$$\text{Minimize } \int_{\Theta} R(\theta; \delta) d\pi(\theta)$$

for some measure  $\pi$ , called prior

If  $\pi$  is probability measure,  
same as  $\mathbb{E}_{\theta \sim \pi} [R(\theta; \delta)]$

$\leadsto$  Bayes estimator

Binomial:  $\delta_1$  is Bayes wrt  $\pi = \lambda$  on  $[0, 1]$

$\delta_2$  also Bayes wrt  $\pi = \text{Beta}(2, 2)$

b) Worst-case risk

$$\text{Minimize } \sup_{\theta} R(\theta; \delta)$$

$\leadsto$  Minimax estimator

Closely related to Bayes

Binomial:  $\delta_2$  is minimax (for  $n=16$ )

2) Restrict choices of estimator

a) Restrict to unbiased estimators:

$$\mathbb{E}_{\theta}[\delta(x)] = g(\theta) \text{ for all } \theta$$

Binomial:  $\delta_0$  is best unbiased estimator